



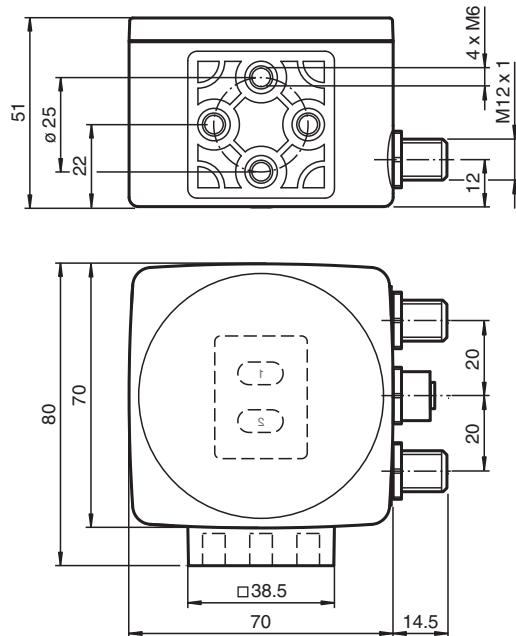
Optical reading head PCV100-F200-B16-V15

- Non-contact positioning on Data Matrix code tape
- Mechanically rugged: no wearing parts, long operating life, maintenance-free
- High resolution and precise positioning, especially for facilities with curves and switch points as well as inclines and declines.
- Travel ranges up to 10 km, in X and Y direction
- CANopen interface

Read head for incident light positioning system



Dimensions



Technical Data

Release date: 2024-12-12 Date of issue: 2024-12-12 Filename: 251412_eng.pdf

General specifications

Passage speed	v	$\leq 8 \text{ m/s}$
Measuring length		max. 10000 m
Light type		Integrated LED lightning (red)
Scan rate		40 s^{-1}
Read distance		100 mm
Depth of focus		$\pm 20 \text{ mm}$
Reading field		50 mm x 30 mm
Ambient light limit		100000 Lux
Resolution		$\pm 0.1 \text{ mm}$

Nominal ratings

Camera

Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

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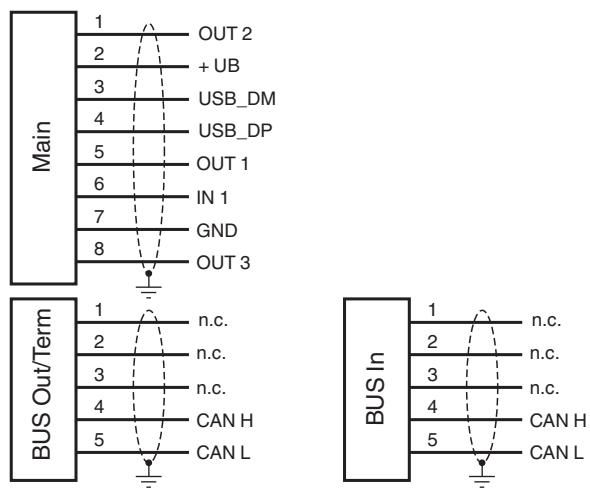
Technical Data

Type	CMOS , Global shutter	
Processor		
Clock pulse frequency	600 MHz	
Speed of computation	4800 MIPS	
Digital resolution	32 Bit	
Functional safety related parameters		
MTTF _d	100 a	
Mission Time (T _M)	20 a	
Diagnostic Coverage (DC)	0 %	
Indicators/operating means		
LED indication	7 LEDs (communication, alignment aid, status information)	
Electrical specifications		
Operating voltage	U _B	15 ... 30 V DC , PELV
No-load supply current	I ₀	max. 400 mA
Power consumption	P ₀	6 W
Interface		
Interface type	CANopen , galvanically isolated	
Data output code	binary code	
Transfer rate	max. 1 MBit/s	
Interface 2		
Interface type	USB Service	
Input		
Input type	1 function input 0-level: -U _B or unwired 1-level: +8 V ... +U _B , programmable	
Input impedance	≥ 27 kΩ	
Output		
Output type	1 to 3 switch outputs , programmable , short-circuit protected	
Switching voltage	Operating voltage	
Switching current	150 mA each output	
Conformity		
Photobiological safety	exempt group according to EN 62471:2008	
Standard conformity		
Emitted interference	EN 61000-6-4:2007+A1:2011	
Noise immunity	EN 61000-6-2:2005	
Shock resistance	EN 60068-2-27:2009	
Vibration resistance	EN 60068-2-6:2008	
Approvals and certificates		
CE conformity	CE	
UKCA conformity	UKCA	
UL approval	cULus Listed, General Purpose, Class 2 Power Source, Type 1 enclosure	
CCC approval	CCC approval / marking not required for products rated ≤36 V	
Ambient conditions		
Operating temperature	0 ... 60 °C (32 ... 140 °F) , -20 ... 60 °C (-4 ... 140 °F) (noncondensing; prevent icing on the lens!)	
Storage temperature	-20 ... 85 °C (-4 ... 185 °F)	
Relative humidity	90 % , noncondensing	
Mechanical specifications		
Connection type	8-pin, M12x1 connector, standard (supply+IO) 5-pin, M12x1 socket, A-coded (bus out/termination) 5-pin, M12x1 connector, A-coded (bus in)	
Degree of protection	IP67	
Material		
Housing	PC/ABS	
Mass	approx. 200 g	

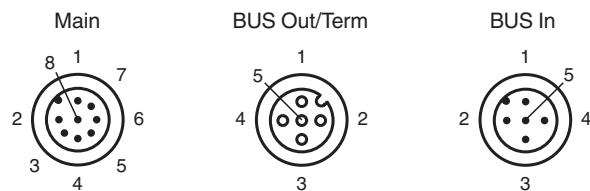
Technical Data

Dimensions	
Height	70 mm
Width	70 mm
Depth	50 mm

Connection

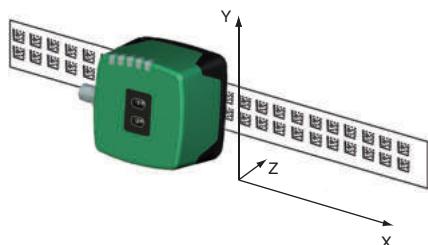


Connection Assignment

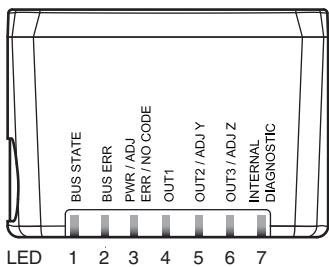
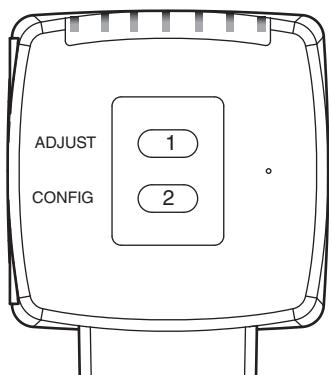


Characteristic Curve

Coordinates



Characteristic Curve



Additional Information

General

The PCV... reading head is part of the positioning system in the method for measurement by Pepperl+Fuchs. It consists of a camera module and an integrated illumination unit among other things. The reading head detects position marks, which are put on an adhesive code band in the form of Data Matrix code. The mounting of the code band is as a rule stationary on a firm part of the plant (elevator shaft, overhead conveyor mounting rails...); that of the reading head is parallel on the moving "vehicle" (elevator car, overhead conveyor chassis...).

Mounting and commissioning

Mount the reading head such that its optical surface captures the optimal read distance to the code band (see Technical Data). The stability of the mounting and the guidance of the vehicle must be provided such that the depth of field of the reading head is not closed during operation. All reading heads can be optimally customized by parameterization for specific requirements.

Displays and Controls

The PCV... reading head allows visual function check and fast diagnosis with 7 indicator LEDs. The reading head has 2 buttons on the reverse of the device to activate the alignment aid and parameterization mode.

LEDs

LED	Color	Label	Meaning
1	Yellow	BUS STATE	CANopen communication active
2	Red	BUS ERR	CANopen communication Error
3	Green/red	PWR/ADJ ERR/NO CODE	Code recognized/not recognized, Error
4	Yellow	OUT1	Output 1, configuration
5	Yellow	OUT2/ADJ Y	Output 2, Alignment aid Y
6	Yellow	OUT3/ADJ Z	Output 3, Alignment aid Z
7	red/green/yellow	INTERNAL DIAGNOSTICS	Internal diagnostics

External parameterization

For external parameterization you require the parameterization code as Data Matrix with the desired reading head parameters. Data Matrix code cards for step-by-step external parameterization are printed in the reading heads operating instructions.

Parameterization is only possible within 10 minutes of switching on the reading head. If a button is pressed after 10 minutes subsequent to switching on, there is visual signaling via the LEDs (LED1, yellow/LED2, red/LED3, green/LED4, yellow/LED5, yellow/LED6, yellow flash for 2 seconds)

- The switchover from normal operation to parameterization mode is via button 2 on the reverse of the reading head. Button 2 must be pressed for more than 2 seconds. LED4 now flashes.
- **Note:** Parameterization mode automatically ends after 1 minute of inactivity. The reading head returns to normal operation and works with unchanged settings.
- Place the parameterization code in the view of the camera module. After recognition of the parameterization code, the green LED3 lights up for 1s. In the event of an invalid parameterization code, the red LED3 lights up for 2 s.
- A short press on button 2 ends the parameterization mode and the changed parameters are not stored volatile in the reading head.

Alignment aid for the Y and Z coordinates

The activation of the alignment aid is only possible within 10 minutes of switching on the reading head. The switchover from normal operation to "alignment aid operating mode" is via button 1 on the reverse of the reading head.

- Press the button 1 for longer than 2 s. LED3 flashes green for a recognized code band. LED3 flashes red for an unrecognized code band.
- Z coordinate: If the distance of the camera to the code band too small, the yellow LED6 lights up. If the distance of the camera to the code band too large, the yellow LED6 lights up. Within the target range, the yellow LED6 flashes at the same time as the green LED3.
- Y coordinate: If the optical axis of the camera is too deep in relation to the middle of the code band, the yellow LED5 lights up. If the optical axis is too high, the yellow LED5 extinguishes. Within the target range, the yellow LED5 flashes at the same time as the green LED3.
- A short press on button 1 ends the alignment aid and the reading head changes to normal operation.